

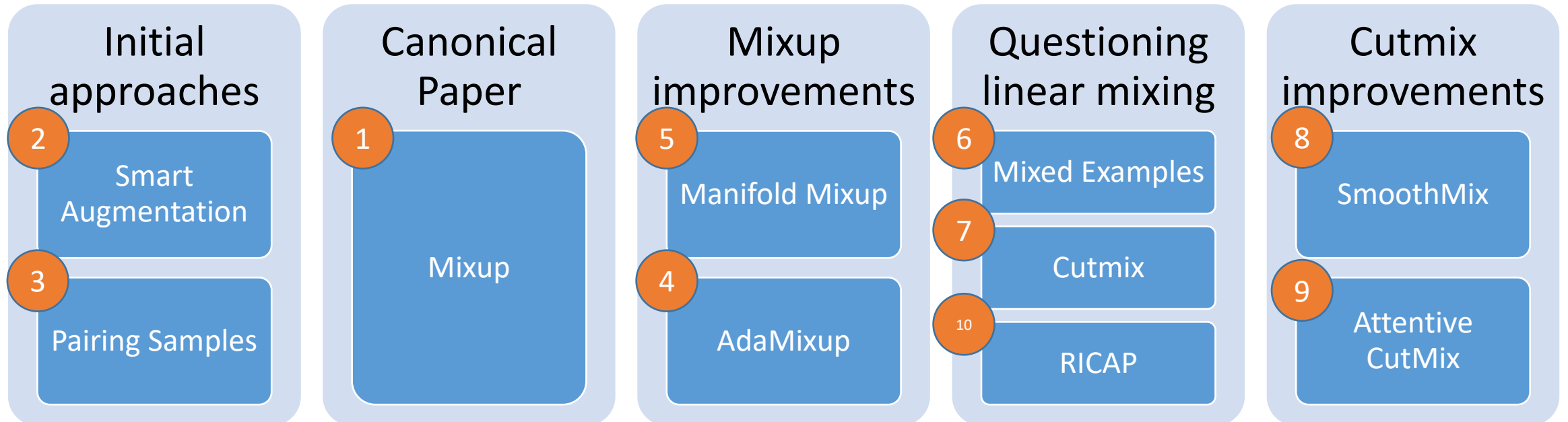
Data Augmentation via Mixing Images – part 2

Dominik Lewy

Data Augmentation via Mixing Images

$$\tilde{x} = \mathbf{B} \odot x_1 + (\mathbf{1} - \mathbf{B}) \odot x_2$$

$$\tilde{y} = \lambda y_1 + (1 - \lambda)y_2$$



Data Augmentation via Mixing Images

Image 1 -
label: boat



Image 2 -
label: airplane



1

Mixup -
label: (boat:0.7, airplane:0.3)



3

SamplePairing -
label: boat



Data Augmentation via Mixing Images

Image 1 -
label: boat



Image 2 -
label: airplane



7

CutMix -
label: (boat:0.7, airplane:0.3)



8

SmoothMix -
label: (boat:0.7, airplane:0.3)



9

AttentiveMix -
label: (boat:0.86, airplane:0.14)



Data Augmentation via Mixing Images

Image 1 -
label: boat



Image 2 -
label: airplane



Image 3 -
label: cow



Image 4 -
label: dog



10

RICAP -
label: (dog:0.15, cow:0.07,
airplane:0.52, boat:0.26)



Data Augmentation via Mixing Images

6

Image 1 -
label: boat



Image 2 -
label: airplane



Vertical Concat -
label: (boat:0.7, airplane:0.3)



Horizontal Concat -
label: (boat:0.7, airplane:0.3)



Mixed Concat -
label: (boat:0.4, airplane:0.6)



Random 2x2 -
label: (boat:0.5, airplane:0.5)



Random Column Interval -
label: (boat:0.7, airplane:0.3)



Random Row Interval -
label: (boat:0.7, airplane:0.3)



Random Columns -
label: (boat:0.7, airplane:0.3)



Random Rows -
label: (boat:0.7, airplane:0.3)



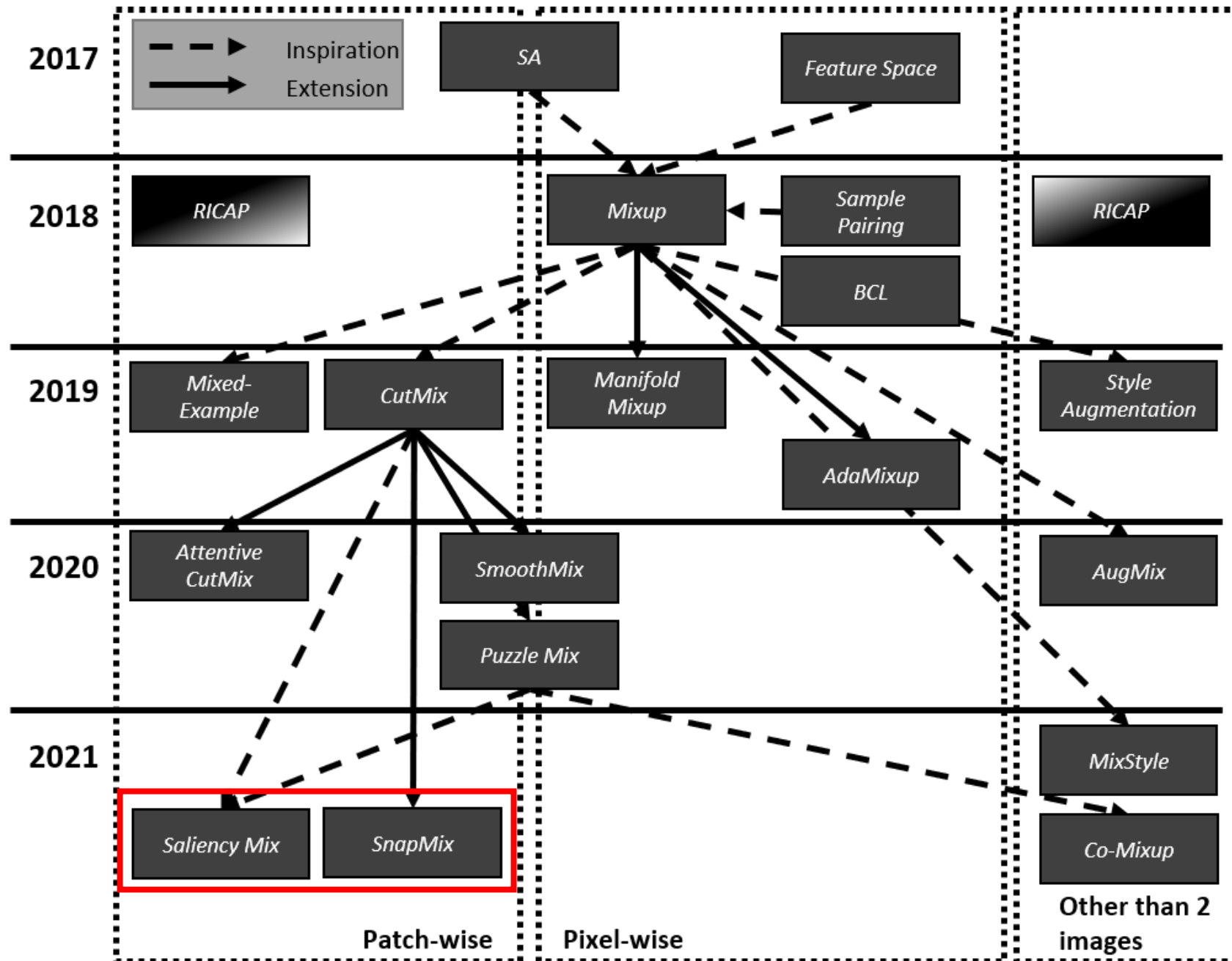
Random Pixels -
label: (boat:0.7, airplane:0.3)



Random Elements -
label: (boat:0.7, airplane:0.3)



Data Augmentation – literature review – Dominik Lewy



SnapMix

SNAPMIX - Shaoli Huang, Xinchao Wang, Dacheng Tao (AAAI 2021). SnapMix: Semantically Proportional Mixing for Augmenting Fine-grained Data.

Image 1 -
label: boat



Heatmap Image 1 -
for class: boat

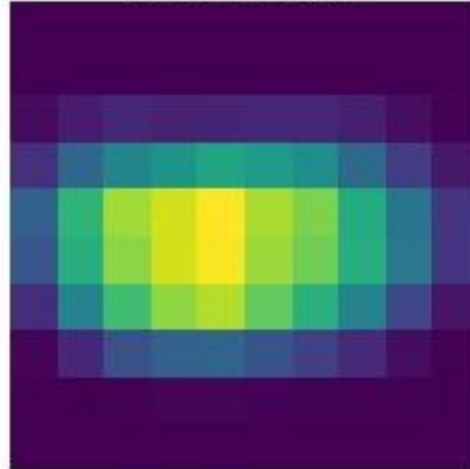
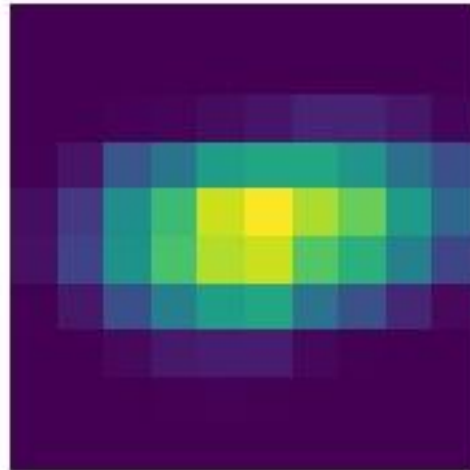


Image 2 -
label: airplane



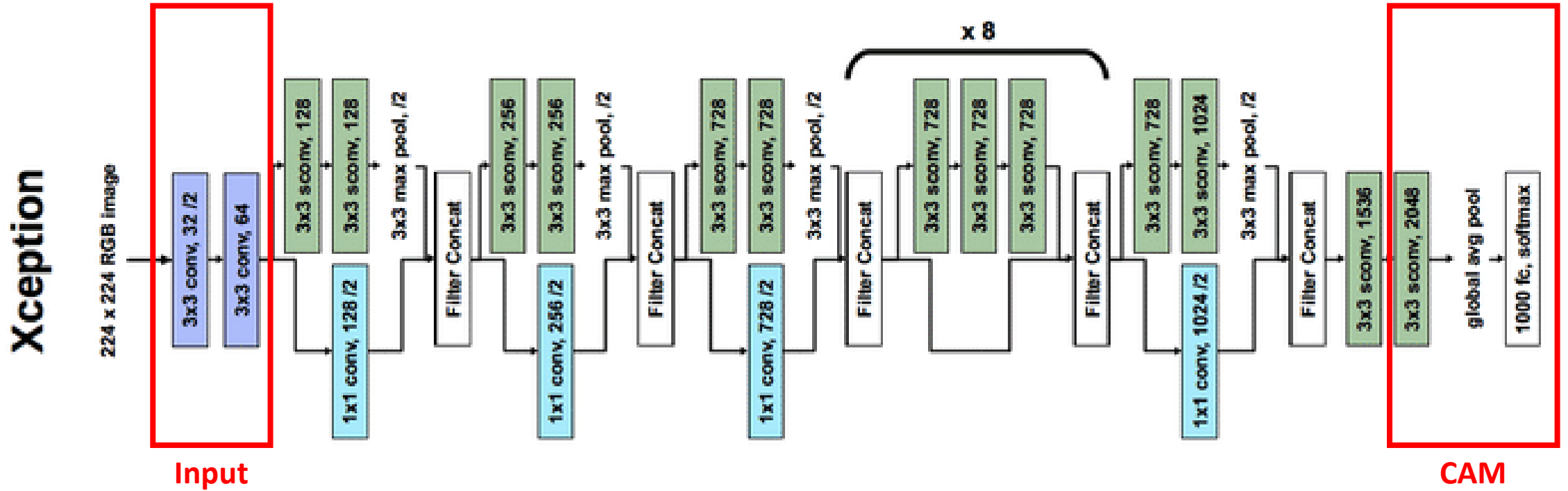
Heatmap Image 2 -
for class: airplane



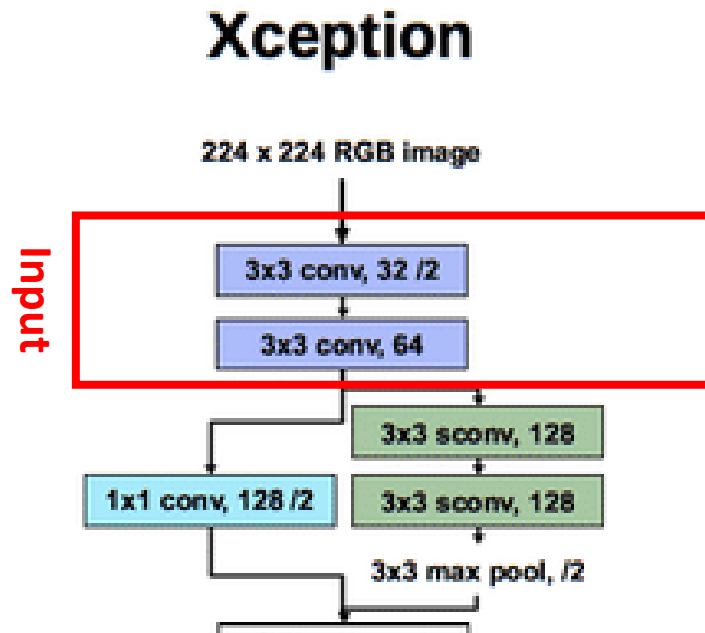
SnapMix -
label: (boat:0.8, airplane:0.0)



Class Activation Map (CAM) on Xception architecture example

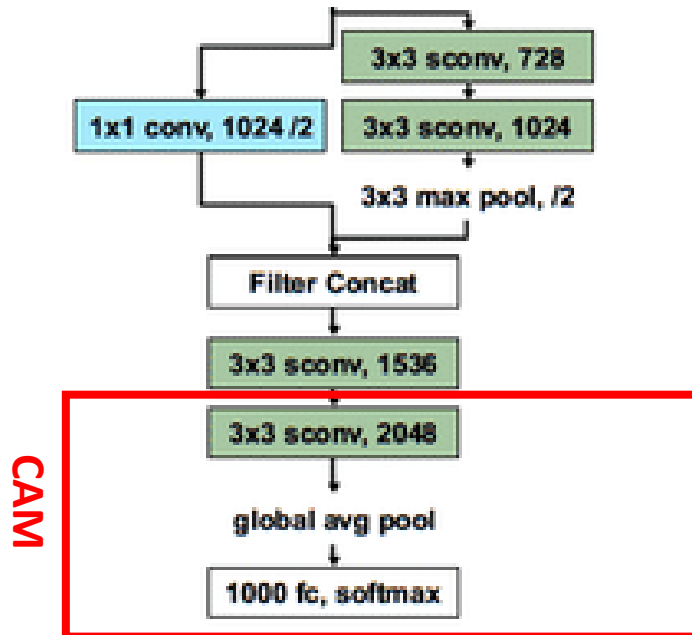


Class Activation Map (CAM) on Xception architecture example



Layer (type)	Output Shape	Param #	Connected to
input_1 (InputLayer)	[(None, 299, 299, 3)]	0	
block1_conv1 (Conv2D)	(None, 149, 149, 32)	864	input_1[0][0]
block1_conv1_bn (BatchNormaliza)	(None, 149, 149, 32)	128	block1_conv1[0][0]
block1_conv1_act (Activation)	(None, 149, 149, 32)	0	block1_conv1_bn[0][0]
block1_conv2 (Conv2D)	(None, 147, 147, 64)	18432	block1_conv1_act[0][0]
block1_conv2_bn (BatchNormaliza)	(None, 147, 147, 64)	256	block1_conv2[0][0]
block1_conv2_act (Activation)	(None, 147, 147, 64)	0	block1_conv2_bn[0][0]
block2_sepconv1 (SeparableConv2)	(None, 147, 147, 128)	8768	block1_conv2_act[0][0]
block2_sepconv1_bn (BatchNormal)	(None, 147, 147, 128)	512	block2_sepconv1[0][0]
block2_sepconv2_act (Activation)	(None, 147, 147, 128)	0	block2_sepconv1_bn[0][0]

Class Activation Map (CAM) on Xception architecture example



batch_normalization_3 (BatchNor	(None, 10, 10, 1024)	4096	conv2d_3[0][0]
add_11 (Add)	(None, 10, 10, 1024)	0	block13_pool[0][0] batch_normalization_3[0][0]
block14_sepconv1 (SeparableConv	(None, 10, 10, 1536)	1582080	add_11[0][0]
block14_sepconv1_bn (BatchNorma	(None, 10, 10, 1536)	6144	block14_sepconv1[0][0]
block14_sepconv1_act (Activatio	(None, 10, 10, 1536)	0	block14_sepconv1_bn[0][0]
block14_sepconv2 (SeparableConv	(None, 10, 10, 2048)	3159552	block14_sepconv1_act[0][0]
block14_sepconv2_bn (BatchNorma	(None, 10, 10, 2048)	8192	block14_sepconv2[0][0]
block14_sepconv2_act (Activatio	(None, 10, 10, 2048)	0	block14_sepconv2_bn[0][0]
avg_pool (GlobalAveragePooling2	(None, 2048)	0	block14_sepconv2_act[0][0]
predictions (Dense)	(None, 1000)	2049000	avg_pool[0][0]

Class Activation Map (CAM) on Xception architecture example

7	9	10	4
9	10	3	9
6	2	0	3
2	0	0	1

Max Pooling

10	10
6	3

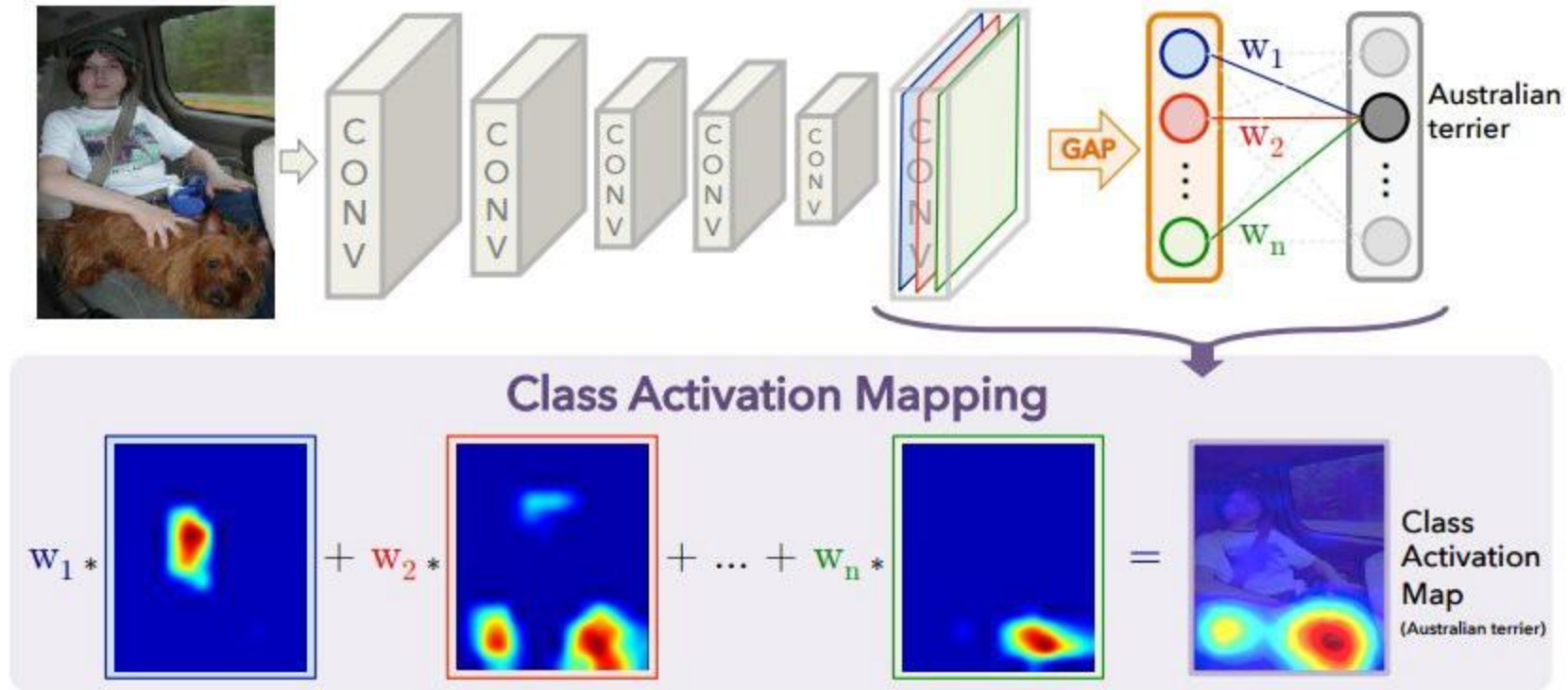
<https://www.di.ens.fr/~josef/publications/Oquab15.pdf>

Average Pooling

8.8	6.5
2.5	1

<https://arxiv.org/pdf/1512.04150.pdf>

Class Activation Map (CAM) on Xception architecture example



Class Activation Map (CAM) on Xception architecture example



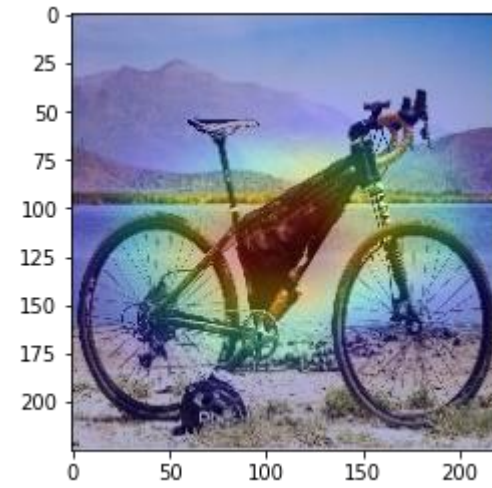
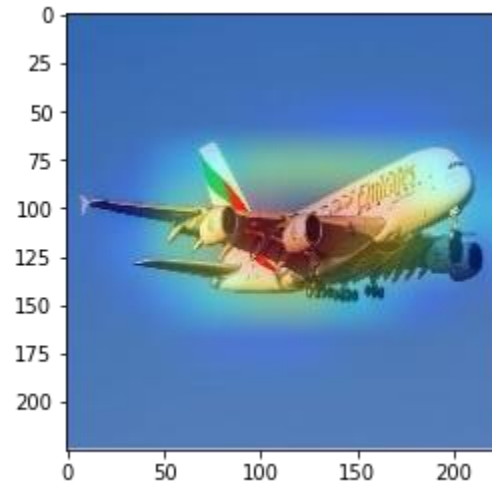
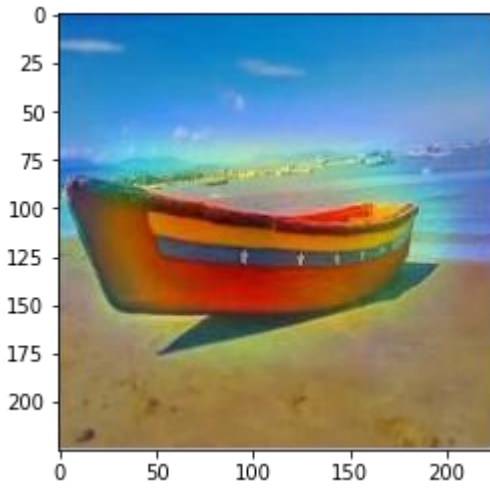
canoe



airliner

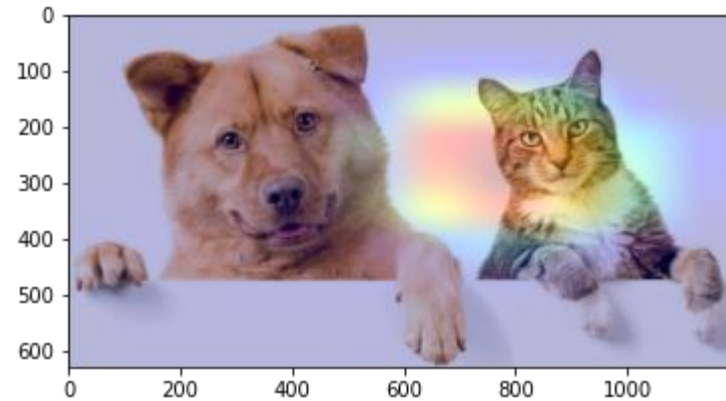
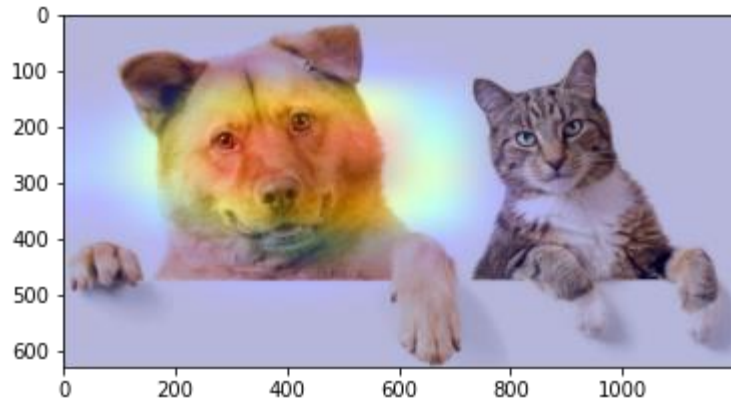


mountain_bike



Class Activation Map (CAM) on Xception architecture example

Predicted: [('n02112137', 'chow', 0.06336529), ('n02124075', 'Egyptian_cat', 0.050370798)]





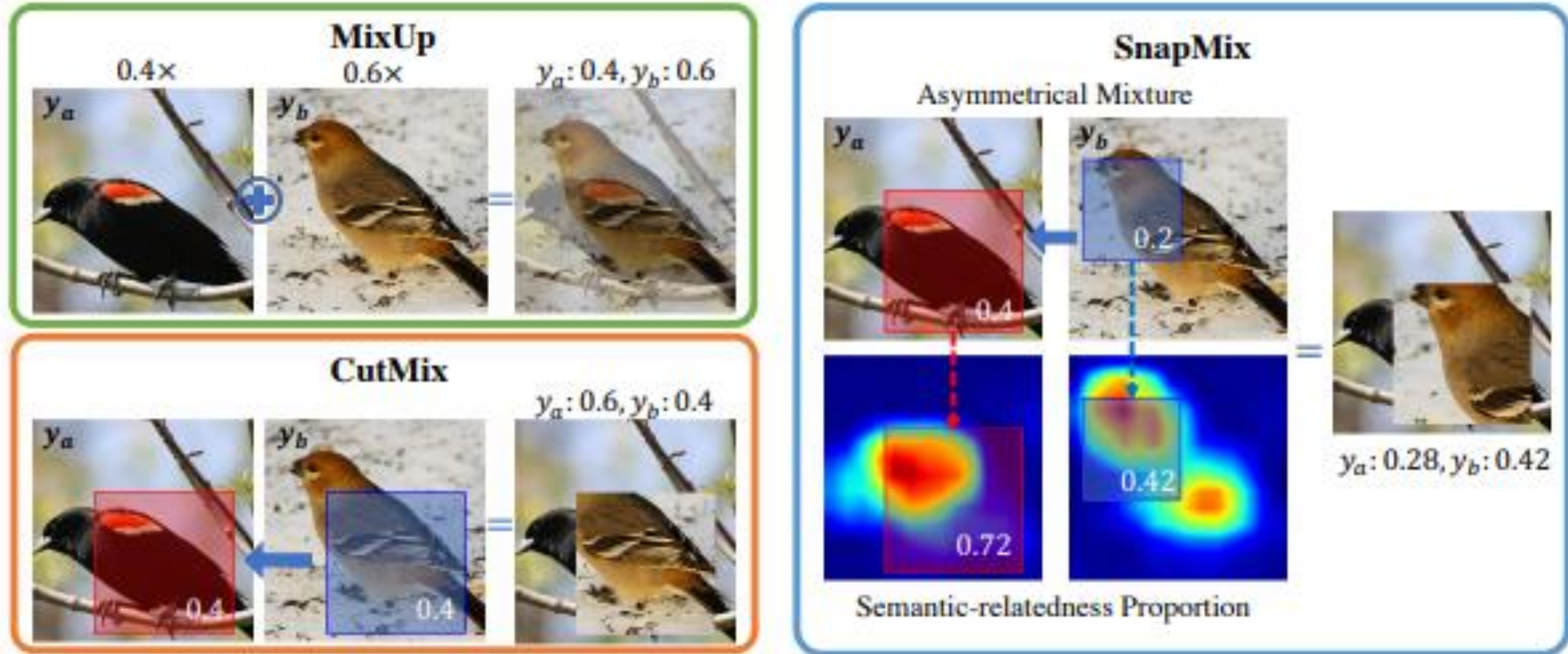
6/17/2021



6/17/2021

SnapMix

SNAPMIX - Shaoli Huang, Xinchao Wang, Dacheng Tao (AAAI 2021). SnapMix: Semantically Proportional Mixing for Augmenting Fine-grained Data.



SnapMix

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$$\tilde{x} = (I - B_{\lambda^1}) \odot x_1 + T_{\theta}(B_{\lambda^2} \odot x_2)$$

where B_{λ^1} and B_{λ^2} are two binary masks containing random box regions with the area ratio λ^1 and λ^2 , respectively, and T_{θ} is a function that maps the patch from x_2 onto the patch in x_1 .

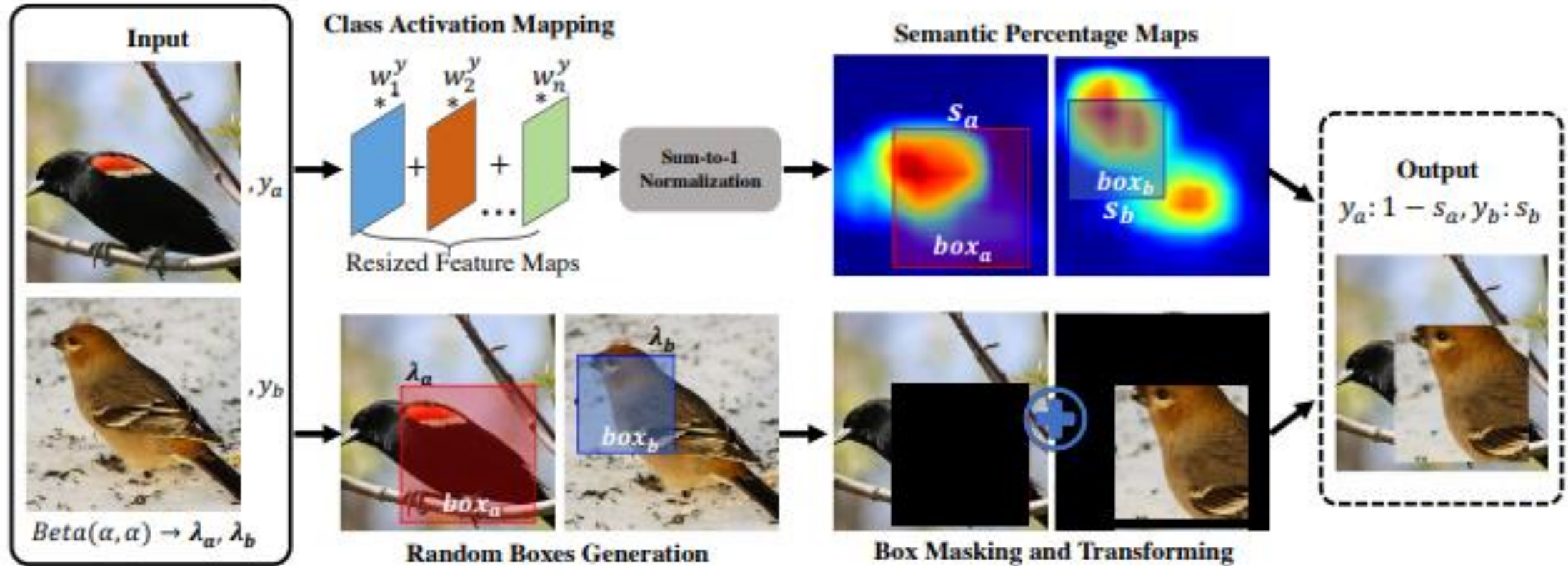
$$S(x_i) = \frac{CAM(x_i)}{sum(CAM(x_i))}$$

$$p_1 = 1 - sum(B_{\lambda^1} \odot S(x_1)), \quad p_2 = sum(B_{\lambda^2} \odot S(x_2))$$

where $p_1, p_2 \in [0,1]$ are partial labels assigned to classes corresponding to the class of images 1 and 2, respectively.

SnapMix

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SnapMix

SNAPMIX - Shaoli Huang, Xinchao Wang, Dacheng Tao (AAAI 2021). SnapMix: Semantically Proportional Mixing for Augmenting Fine-grained Data.

Table 1: Performance comparison(Mean Acc.%) of methods using backbone networks *Resnet-18* and *Resnet-34* on fine-grained datasets. Each method's improvement over the baseline is shown in the brackets.

	CUB		Cars		Aircraft	
Baseline	Res18	Res34	Res18	Res34	Res18	Res34
Baseline	82.35	84.98	91.15	92.02	87.80	89.92
CutOut	80.54 (-1.81)	83.36 (-1.62)	91.83(+0.68)	92.84 (+0.82)	88.58 (+0.78)	89.90 (-0.02)
MixUp	83.17 (+0.82)	85.22 (+0.24)	91.57 (+0.42)	93.28 (+1.26)	89.82 (+2.02)	91.02 (+1.1)
CutMix	80.16 (-2.19)	85.69 (+0.71)	92.65 (+1.50)	93.61 (+1.59)	89.44 (+1.64)	91.26 (+1.34)
SnapMix	84.29 (+1.94)	87.06 (+2.08)	93.12(+1.97)	93.95 (+1.93)	90.17 (+2.37)	92.36 (+2.44)

Table 2: Performance comparison(Mean Acc.%) of methods using backbone networks *Resnet-50* and *Resnet-101* on fine-grained datasets. Each method's improvement over the baseline is shown in the brackets.

	CUB		Cars		Aircraft	
Baseline	Res50	Res101	Res50	Res101	Res50	Res101
Baseline	85.49	85.62	93.04	93.09	91.07	91.59
CutOut	83.55 (-1.94)	84.70 (-0.92)	93.76 (+0.72)	94.16 (+1.07)	91.23 (+0.16)	91.79 (+0.2)
MixUp	86.23 (+0.74)	87.72 (+2.1)	93.96 (+0.92)	94.22 (+1.13)	92.24 (+1.17)	92.89 (+1.3)
CutMix	86.15 (+0.66)	87.92 (+2.3)	94.18 (+1.14)	94.27 (+1.18)	92.23 (+1.16)	92.29 (+0.7)
SnapMix	87.75 (+2.26)	88.45 (+2.83)	94.30 (+1.21)	94.44 (+1.35)	92.80 (+1.73)	93.74 (+2.15)

SnapMix

SNAPMIX - Shaoli Huang, Xinchao Wang, Dacheng Tao (AAAI 2021). SnapMix: Semantically Proportional Mixing for Augmenting Fine-grained Data.

Key points:

- The method is **dedicated to fine-grained image classification problem**, in which classes differentiate by details only
- Modification of CutMix in the two following aspects:
 - the way of label vector calculation for the mixed sample
 - **independent selection of the size and placement of the patch** in each of the two input images (the patch is not automatically pasted in the corresponding location of the target image).
- In order to calculate the label for the augmented image, the class activation map (CAM) is used.
 - CAM is a transformation applied on top of the last convolutional layer of the network so as to point locations of the class-discriminative features.
- The output of CAM is normalized to get Semantic Percent Map (SPM)
- An interesting aspect of the method is the **lack of a constraint that partial labels should sum up to 1**. This way it is possible to indicate in the label that as a result of the operation one image has become relatively more / less relevant than previously (for instance, when the patch masked a discriminative feature in that image).
- Another relevant SnapMix feature is **the ability to offer more effective augmentations as the training process progresses**. This is due to the fact that CAM works on top of the classifier, and therefore, becomes more accurate along with the classification improvement, making the resulting augmented samples more effective.

Saliency Mix

SALIENCY MIX - A F M Shahab Uddin, Mst. Sirazam Monira, Wheemyung Shin, TaeChoong Chung, Sung-Ho Bae (ICLR 2021). SaliencyMix: A Saliency Guided Data Augmentation Strategy for Better Regularization.

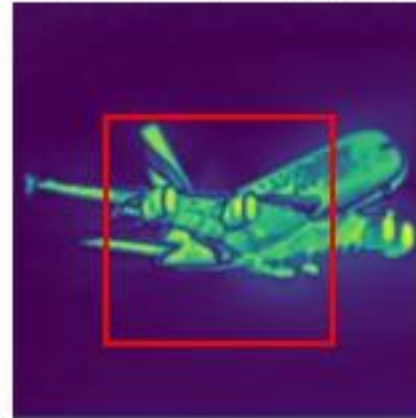
Image 1 -
label: boat



Image 2 -
label: airplane



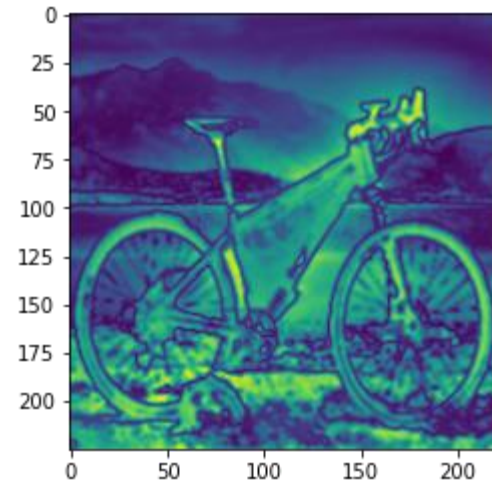
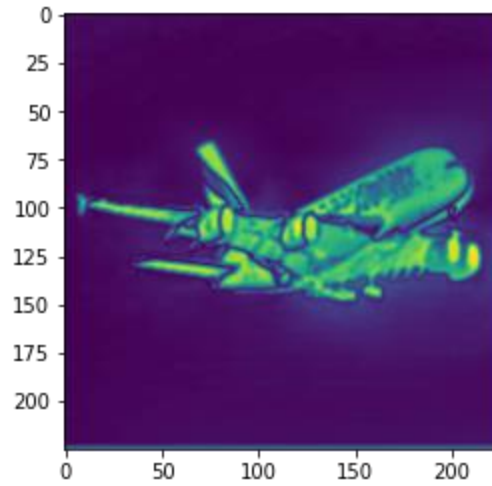
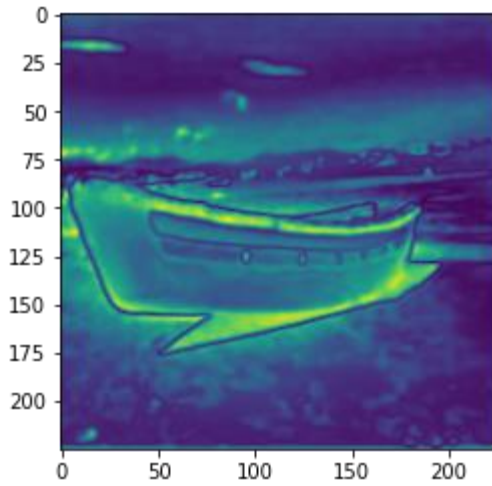
Saliency map - Image 1 -
with saliency peak indicated



SaliencyMix -
label: (boat:0.3, airplane:0.7)







Saliency Calculation



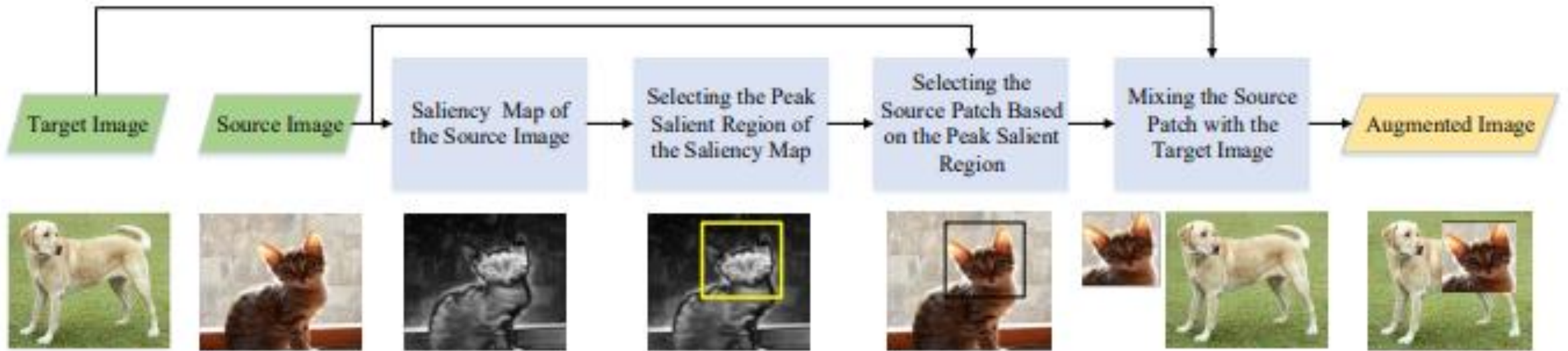
Saliency Mix

SALIENCY MIX - A F M Shahab Uddin, Mst. Sirazam Monira, Wheemyung Shin, TaeChoong Chung, Sung-Ho Bae (ICLR 2021). SaliencyMix: A Saliency Guided Data Augmentation Strategy for Better Regularization.

	Original Image	Label	Augmented Image	Augmented Label
Target Image		Dog		Dog - 80% ? Cat - 20% ?
Source Image		Cat		Dog - 80% ? Cat - 20% ?

Saliency Mix

SALIENCY MIX - A F M Shahab Uddin, Mst. Sirazam Monira, Wheemyung Shin, TaeChoong Chung, Sung-Ho Bae (ICLR 2021). SaliencyMix: A Saliency Guided Data Augmentation Strategy for Better Regularization.



Saliency Mix

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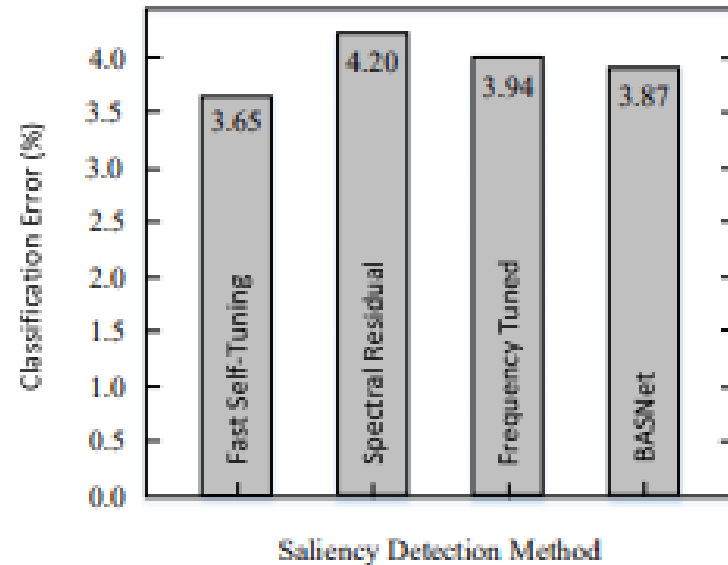


Figure 3. The effect of using different saliency detection methods on the proposed SaliencyMix data augmentation. Performances are reported from the average of five runs.

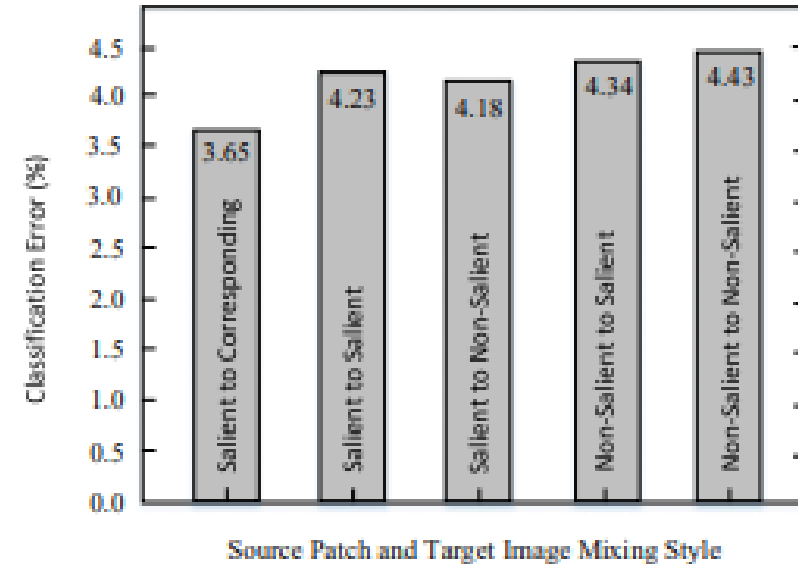


Figure 4. Different ways of mixing the source patch with the target image and their effects. Performances are reported from the average of five runs.

Saliency Mix

SALIENCY MIX - A F M Shahab Uddin, Mst. Sirazam Monira, Wheemyung Shin, TaeChoong Chung, Sung-Ho Bae (ICLR 2021). SaliencyMix: A Saliency Guided Data Augmentation Strategy for Better Regularization.

Table 1. Classification performance (average of five runs) of SOTA data augmentation methods on CIFAR-10 and CIFAR-100 datasets using popular standard architectures. An additional "+" sign after the dataset name indicates that the traditional data augmentation techniques have also been used during training.

METHOD	TOP-1 ERROR (%)			
	CIFAR-10	CIFAR-10+	CIFAR-100	CIFAR-100+
RESNET-18 (BASELINE)	10.63±0.26	4.27±0.21	36.68±0.57	22.46±0.31
RESNET-18 + CUTOUT	9.31±0.18	3.99±0.13	34.98±0.29	21.96±0.24
RESNET-18 + CUTMIX	9.44±0.34	3.78±0.12	34.42±0.27	19.42±0.23
RESNET-18 + SALIENCYMIX	7.59±0.22	3.65±0.10	28.73±0.13	19.29±0.21
RESNET-50 (BASELINE)	12.14±0.95	4.98±0.14	36.48±0.50	21.58±0.43
RESNET-50 + CUTOUT	8.84±0.77	3.86±0.25	32.97±0.74	21.38±0.69
RESNET-50 + CUTMIX	9.16±0.38	3.61±0.13	31.65±0.61	18.72±0.23
RESNET-50 + SALIENCYMIX	6.81±0.30	3.46±0.08	24.89±0.39	18.57±0.29
WIDERESNET-28-10 (BASELINE)	6.97±0.22	3.87±0.08	26.06±0.22	18.80±0.08
WIDERESNET-28-10 + CUTOUT	5.54±0.08	3.08±0.16	23.94±0.15	18.41±0.27
WIDERESNET-28-10 + CUTMIX	5.18±0.20	2.87±0.16	23.21±0.20	16.66±0.20
WIDERESNET-28-10 + SALIENCYMIX	4.04±0.13	2.76±0.07	19.45±0.32	16.56±0.17

Saliency Mix

SALIENCY MIX - A F M Shahab Uddin, Mst. Sirazam Monira, Wheemyung Shin, TaeChoong Chung, Sung-Ho Bae (ICLR 2021). SaliencyMix: A Saliency Guided Data Augmentation Strategy for Better Regularization.

Key points:

- Uses saliency information to **find the most representative pixels**
- The patch is either centered on the most salient pixel (if the entire patch fits within the image) or keeps this pixel within the patched area (otherwise).
- The authors considered four saliency calculation methods relaying either on statistical approaches or a learning based approach, and eventually decided to use the statistical saliency method as it offered slightly better classification accuracy
- **Invariant to image size**
- Various placements of the salient patch of the image were also tested, including placing the patch on salient / non-salient / corresponding part of the other image, with a conclusion that the choice of a **corresponding place is the best option in terms of regularization.**

Important patches detection on example of SaliencyMix vs. SnapMix

Vector	SaliencyMix	SnapMix
Algorithm used	Montabone & Soto	Class Activation Mapping
Type	Statistical method	Learning based model
Input image size	No limitations	Limited to the input size of the architecture used
Scope of important objects detection	No limitations	Limited to the classes the network was trained on

The end.
Thank you!

Discussion

Methods for identifying important signals in different modalities?